

PDFO

A Cross-Platform MATLAB/Python Interface for Powell's Derivative-Free Optimization Solvers

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Table of contents

1. Introduction
2. Powell's derivative-free solvers
3. The PDFO package
4. Summary and conclusion

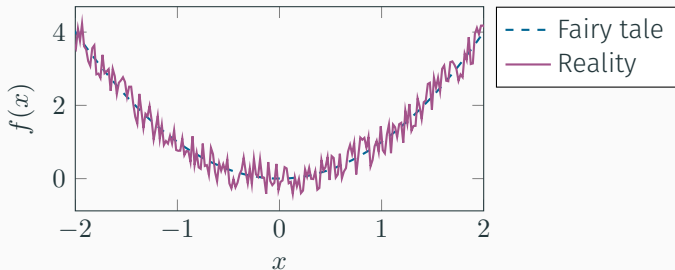
Introduction

Derivative-free optimization (DFO)

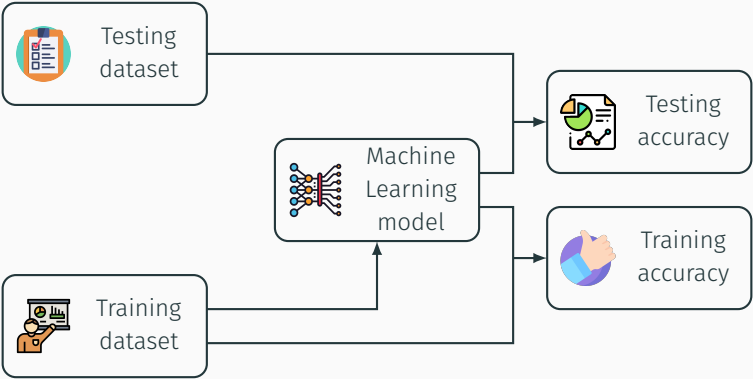
- Minimize a function f using function values but not derivatives.
- f can be a black-box resulting from experiments or simulations.

$$x \in \Omega \subseteq \mathbb{R}^n \longrightarrow f: \mathbb{R}^n \rightarrow \mathbb{R} \longrightarrow f(x)$$

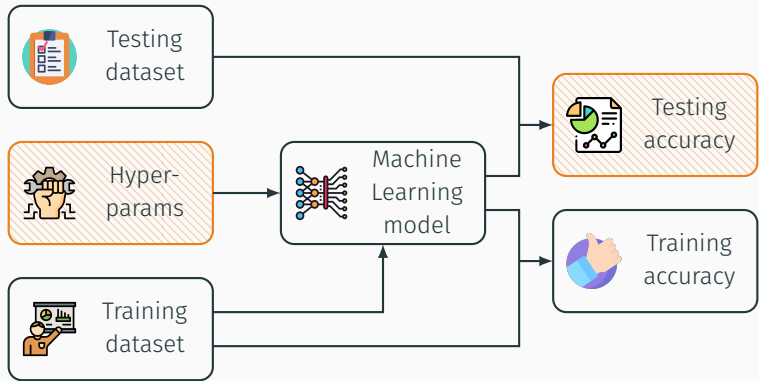
- f may be smooth, but ∇f cannot be numerically evaluated.
- Evaluations of f can be noisy and expensive.



An example of DFO problem



An example of DFO problem



How to **optimize** the accuracy of the model by tuning the **hyperparameters**? What is the gradient of the performance of the model (e.g., testing accuracy) with respect to the hyperparameters?

Powell's derivative-free solvers

Two paradigms of methods

- **Direct-search methods**: sampling iteratively f at a finite number of points and choosing the iterates using simple comparisons.
 - *Examples*: Nelder-Mead, GPS, MADS, BFO, ...
- **Model-based methods**: modeling iteratively f using simple functions and choosing the iterates by minimizing the models.
 - *Globalization*: embedded in **trust-region** or line-search frameworks.
 - *Examples*: Powell's solvers, DFO, ORBIT, BOOSTERS, DFO-LS, ...

Idea of trust-region frameworks

Given a model f_k of f around x_k , the trial step d_k approximates

$$\arg \min \{ f_k(x_k + d) : x_k + d \in \Omega_k, \|d\| \leq \Delta_k \},$$

where Δ_k is the trust-region radius and $\Omega_k \approx \Omega$ around x_k . Accept the trial point $x_k + d_k$ if it satisfies some **reduction condition**, and update the trust-region radius Δ_k accordingly.

General overview of the Powell's derivative-free solvers

Powell developed five **derivative-free trust-region** solvers.

Solvers	References	Constraint types	Model types
COBYLA	Powell (1994)	nonlinear	linear (FD ¹)
UOBYQA	Powell (2002)	unconstrained	quadratic (FD)
NEWUOA	Powell (2006)	unconstrained	quadratic (UD ²)
BOBYQA	Powell (2009)	bounds	quadratic (UD)
LINCOA	Powell (2015)	linear	quadratic (UD)

¹FD: obtained by fully-determined interpolations.

²UD: obtained by underdetermined interpolations.

Original implementation of the solvers

Powell implemented the five solvers in **Fortran 77** ...

Models for NEWUOA, BOBYQA, and LINCOA

Given a nondegenerate interpolation set $\mathcal{X}_k \subseteq \mathbb{R}^n$, the k th quadratic model f_k of the objective function f solves

$$\begin{aligned} \min \quad & \|\nabla^2 Q - \nabla^2 f_{k-1}\|_F \\ \text{s.t.} \quad & Q(x) = f(x), \quad x \in \mathcal{X}_k, \\ & Q \in \mathcal{Q}_n, \end{aligned}$$

where \mathcal{Q}_n is the set of quadratic functions in \mathbb{R}^n .

- Typically, \mathcal{X}_k has $\mathcal{O}(n)$ elements, instead of $\mathcal{O}(n^2)$.
- At each iteration, at most one point of \mathcal{X}_k is modified, causing an at-most rank-2 update of the KKT matrix of the system.
- Geometry of \mathcal{X}_k is maintained using Lagrange polynomials.

The PDFO package

Current version of the PDFO package

Interfaces for Powell's solvers

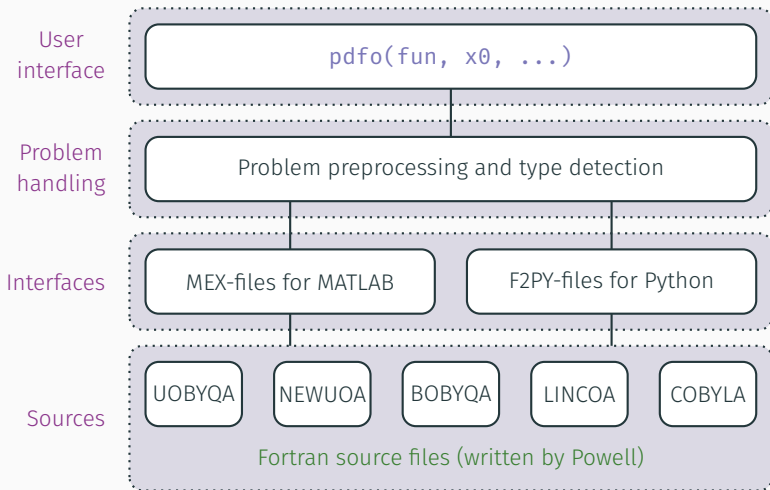
PDFO provides MATLAB/Python **interfaces** for using Powell's derivative-free solvers.

- More **languages** will be added in the future.
- It supports Linux, MacOS, and **even Windows**.
- It is **NOT** a reimplementation, but rather interfaces (reimplementation will come in the future)!



Visit PDFO homepage
<https://www.pdfo.net/>

Current version of the PDFO package



Core features of PDFO

PDFO preprocesses a problem as follows

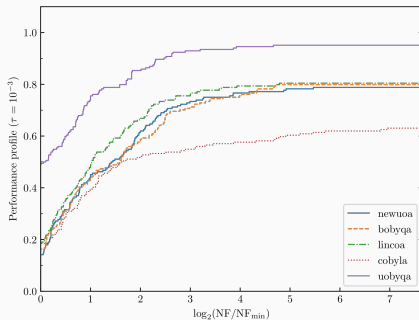
- Detect obvious **infeasibility**.
- Attempt to **project the initial guess** onto the feasible set for linearly-constrained problems.
- Eliminate **linear equality constraints** (QR factorization).
- **Reformulate the constraints** to call the Powell's solvers.
- Handle possible **overflows** and **faults** of the inputs.

Minor modifications to the Fortran source code have been made.

- The original COBYLA code may **NOT return** the best evaluated point.
- The original UOBYQA and LINCOA code might encounter **infinite cyclings** on **ill-conditioned problems**.
- Other programming-related bugs have also been patched.

Comparison of the Powell's solvers using PDFO

We tested PDFO using performance profiles³ on problems from the CUTEst⁴ dataset of Gould, Orban, and Toint (2015).



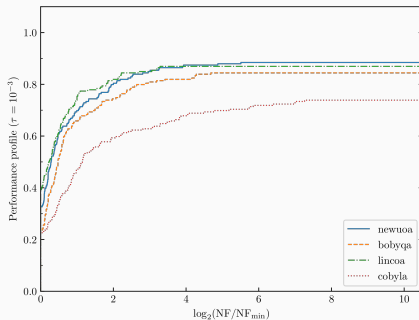
Unconstrained problems of dimensions at most 10

³See Dolan and Moré (2002) and Moré and Wild (2009).

⁴We used the PyCUTEst package by J. Fowkes and L. Roberts.

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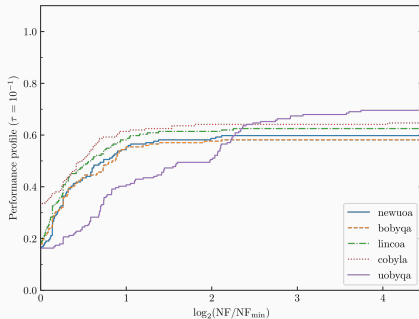
Unconstrained problems of dimensions at most 50

³See Dolan and Moré (2002) and Moré and Wild (2009).

⁴We used the PyCUTEst package by J. Fowkes and L. Roberts.

Comparison of the Powell's solvers using PDFO

We tested PDFO using performance profiles³ on problems from the CUTEst⁴ dataset of Gould, Orban, and Toint (2015).



Unconstrained noisy problems of dimensions at most 10

³See Dolan and Moré (2002) and Moré and Wild (2009).

⁴We used the PyCUTEst package by J. Fowkes and L. Roberts.

A synthetic noisy nonsmooth problem i

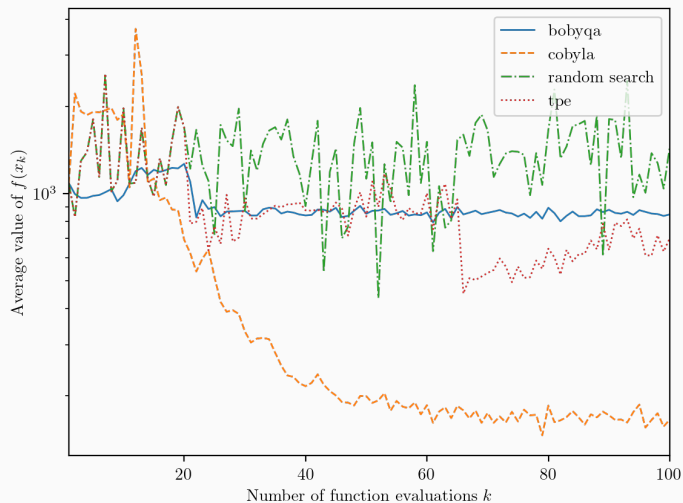
Consider the **noisy Rosenbrock-like nonsmooth** function

$$f(x) = (1 + \sigma e(x))r(x) \quad \text{with} \quad r(x) = \sum_{i=1}^{n-1} 4|x_{i+1} - x_i^2| + |1 - x_i|,$$

where $e(x) \sim \mathcal{N}(0, 1)$ and $\sigma \geq 0$. In our experiment:

- dimension is $n = 10$,
- constraints are $-10 \leq x_i \leq 1/i$ for all $i = 1, 2, \dots, n$,
- noise level is $\sigma = 0.1$,
- budget is **100** function evaluations, and
- number of random experiments is 20.

A synthetic noisy nonsmooth problem ii



A hyperparameter tuning problem

Similarly to Bradley (1997) and Ghanbari and Scheinberg (2017), consider the following **hyperparameter tuning problem**: optimize the **AUC score**⁵ of an SVM (2 hyperparameters) in **binary classification** on given LIBSVM⁶ datasets.

Dataset “splice” (1,000 data, 60 features)

Solvers	No. evaluations	AUC Scores	Testing accuracies
PDFO	65	0.96	0.89
Random search	100	0.64	0.53
Random search	200	0.79	0.53
TPE (Bayesian)	100	0.50	0.50

⁵See Hanley and McNeil (1982).

⁶Available at <https://www.csie.ntu.edu.tw/~cjlin/libsvm/>.

A hyperparameter tuning problem

Similarly to Bradley (1997) and Ghanbari and Scheinberg (2017), consider the following **hyperparameter tuning problem**: optimize the **AUC score**⁵ of an SVM (2 hyperparameters) in **binary classification** on given LIBSVM⁶ datasets.

Dataset “ijcnn1” (49,990 data, 22 features)

Solvers	No. evaluations	AUC Scores	Testing accuracies
PDFO	59	0.99	0.98
Random search	100	0.98	0.97
Random search	200	0.98	0.97
TPE (Bayesian)	100	0.98	0.98

⁵See Hanley and McNeil (1982).

⁶Available at <https://www.csie.ntu.edu.tw/~cjlin/libsvm/>.

Summary and conclusion

Summary and conclusion

- We have developed an **initial version of PDFO**.
 - It provides **MATLAB/Python interfaces** for Powell's DFO solvers.
 - **Encouraging feedbacks** are received from both academia and industry (IRT Saint-Exupéry, Toulouse, France).
 - We made **brief comparisons** with Bayesian optimization.
- We are now working on a **new derivative-free trust-region method** for nonlinear constrained problems, to be included in PDFO.



Thank you!

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